

Week 11: Eigenvalue / Eigenvector.

Recall

Defn: Given a $n \times n$ matrix A , a vector $v \in \mathbb{R}^n$ is said to be an eigenvector of A with eigenvalue $\lambda \in \mathbb{R}$ if

$$Av = \lambda v.$$

Hints from last week:

- 1) To find v and λ , we find $\lambda \in \mathbb{R}$ s.t. $A - \lambda I$ is singular.
Then v is element in $\text{Null}(A - \lambda I)$.
- 2) Some matrix does not have eigenvector.
- 3) The subset $E = \{v \in \mathbb{R}^n \mid Av = \lambda v\}$ is a subspace.

Thm: Let A be a $n \times n$ matrix, v_1, v_2, \dots, v_k be eigenvectors with distinct eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_k$, then v_1, v_2, \dots, v_k are linearly indep.

pf:

Pf by induction: If $k=1$, trivially true.

If the conclusion holds for $k_0 > 0$.

Let $\alpha_1, \alpha_2, \dots, \alpha_{k_0+1} \in \mathbb{R}$ be s.t.

$$\sum_{i=1}^{k_0+1} \alpha_i v_i = 0$$

$$\Rightarrow \sum_{i=1}^{k_0} \alpha_i \lambda_i v_i = -\alpha_{k_0+1} \lambda_{k_0+1} v_{k_0+1} = \lambda_{k_0+1} \left(\sum_{i=1}^{k_0} \alpha_i v_i \right)$$

$$\Rightarrow \sum_{i=1}^{k_0} (\alpha_i \lambda_i - \alpha_i \lambda_{k_0+1}) v_i = 0$$

$$\Rightarrow \alpha_i (\lambda_i - \lambda_{k_0+1}) = 0 \quad \forall i=1, 2, \dots, k_0$$

$$\Rightarrow \alpha_i = 0 \quad \forall i=1, 2, \dots, k_0, \underline{k_0+1} \quad \#$$

By MI, the conclusion holds.

Corollary: If A be a $n \times n$ matrix then A can have at most n distinct eigenvalues.

pf: If A has k distinct eigenvalue $\lambda_1, \lambda_2, \dots, \lambda_k$ with eigenvectors $(v_i)_{i=1}^k$

then $\text{span}\{v_1, v_2, \dots, v_k\}$ is a subspace of \mathbb{R}^n

$$\Rightarrow k \leq n.$$

↓ implication

Ex: $A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{bmatrix}$, $u = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, $v = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$, $w = \begin{bmatrix} 3 \\ 4 \\ 2 \end{bmatrix}$ ← eigenvalues
← eigenvectors

Corollary \Rightarrow these are the only eigenvalues

distinct $\Rightarrow \text{span}\{u, v, w\}$ has $\dim = 3 = \dim(\mathbb{R}^3)$

$$\therefore \text{span}\{u, v, w\} = \mathbb{R}^3.$$

Basis Ex: $A = \begin{bmatrix} \lambda_1 & & 0 \\ 0 & \lambda_2 & \\ & & \ddots \\ 0 & & & \lambda_n \end{bmatrix}$ i.e. $A_{ij} = \begin{cases} \lambda_i & \text{if } i=j \\ 0 & \text{otherwise} \end{cases}$

Notation: $A = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$

Interested in those A which are similar to diagonal matrix.

Defn: Let A be a $n \times n$ matrix

(a) Suppose U is a $n \times n$ invertible matrix, $U^{-1}AU$ is said to be a diagonalization of A iff $U^{-1}AU$ is diagonal

(b) A is called diagonalizable iff $\exists U$, $n \times n$ invertible s.t. $U^{-1}AU$ is a diagonalization of A .

Q: How to find U above??

Ex: $A = \begin{bmatrix} 13 & 30 \\ -6 & -14 \end{bmatrix}$ find U and eigenvalues (if exists).

$A - \lambda I = \begin{bmatrix} 13 - \lambda & 30 \\ -6 & -14 - \lambda \end{bmatrix}$ is singular $\Leftrightarrow \text{rank}(A - \lambda I) = 1$.
($\text{rank} = 2 \Rightarrow$ non-singular)

i.e. $\begin{cases} 13 - \lambda = 30\beta \\ -6 = (-14 - \lambda)\beta \end{cases}$ for some $\beta \neq 0 \in \mathbb{R}$

Solving quadratic eqn $\Rightarrow \lambda = 1$ or -2 .

$$u = \begin{bmatrix} 5 \\ -2 \end{bmatrix} \quad v = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$u \in \text{Null}(A - I)$; $v \in \text{Null}(A + 2I)$.

Goal: Looking for U s.t. $U^{-1}AU = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$.

i.e. $U^{-1}AU \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \lambda_1 \\ 0 \end{bmatrix} = \lambda_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, and $U^{-1}AU \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \lambda_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$\Leftrightarrow A \left(U \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right) = \lambda_1 \left(U \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)$ and $A \left(U \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) = \lambda_2 \left(U \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right)$

$$\text{Hope: } \begin{cases} U \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = u & \text{where } Au = u \\ U \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = v & \text{where } Av = -2v. \end{cases}$$

$$\text{Hence } U = [u, v] = \begin{bmatrix} 5 & 2 \\ -2 & 4 \end{bmatrix}$$

checking: • U is invertible since $\{u, v\}$ are linearly indep
 • $Ue_1 = u$, $Ue_2 = v$.

$$\text{Ex 7: } A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{bmatrix}, \quad u_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad u_2 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad u_3 = \begin{bmatrix} 3 \\ 4 \\ 2 \end{bmatrix}$$

← eigenvector
← eigenvalue

$$\text{write } G = [u_1, u_2, u_3] = \begin{bmatrix} 1 & 1 & 3 \\ 0 & 0 & 4 \\ 0 & 0 & 2 \end{bmatrix} \text{ is invertible.}$$

$$\bullet AGe_i = Au_i = \lambda_i u_i = \lambda_i Ge_i$$

$$\Rightarrow (G^{-1}AG)e_i = \lambda_i e_i \Rightarrow \text{diagonal}$$

(why: If B is $n \times n$ matrix, then the k -th column of $B = B \cdot e_k$)

$$\text{Finding } G^{-1}: \left[\begin{array}{ccc|ccc} 1 & 1 & 3 & 1 & 0 & 0 \\ 0 & 0 & 4 & 0 & 1 & 0 \\ 0 & 0 & 2 & 0 & 0 & 1 \end{array} \right] \rightarrow [I_3 | G^{-1}]$$

$$G^{-1} = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 0 & \frac{1}{2} \\ 0 & 0 & \frac{1}{2} \end{bmatrix}$$

$$\text{checking: } G^{-1}AG = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

True in general!!

Theorem: Let A be $n \times n$ matrix, u_1, u_2, \dots, u_n be vector on \mathbb{R}^n and $G = [u_1 \ u_2 \ \dots \ u_n]$ is non-singular. Then the following are equivalent
(or they form a basis of \mathbb{R}^n)

① u_1, u_2, \dots, u_n are eigenvectors of A with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$ respectively.

② $G^{-1} A G = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$.

Corollary: If $A = n \times n$ matrix has n distinct eigenvalues, then A is diagonalizable.

pf: By assumption, \exists eigenvectors u_1, u_2, \dots, u_n which are linearly indep $\Rightarrow \text{span}\{u_1, u_2, \dots, u_n\} = \mathbb{R}^n$.

$\Rightarrow G$ exists with $G^{-1} A G = \text{diagonal}$.
Invertible

observation: Suppose $A = n \times n$ matrix, then A is singular iff $0 = \text{eigenvalue of } A$.

(And $\forall v \in \text{Null}(A) \Rightarrow v = \text{eigenvector of } A$ with eigenvalue $= 0$)

Theorem: Let A be $n \times n$ matrix. Suppose $\lambda_1, \lambda_2, \dots, \lambda_k$ are all eigenvalues of A . Then the following are equivalent.

① A is diagonalizable (i.e. $\exists U$ invertible st. $U^{-1} A U = \text{diagonal}$)

② $\sum_{i=1}^k \dim(E_A(\lambda_i)) = n$.

Moreover, if ② holds, take $\{v_{ij}\}_{j=1}^{\dim(E_A(\lambda_i))}$ to be basis for $E_A(\lambda_i)$, then

$\{v_{ij} \mid i=1, 2, \dots, k; j=1, 2, \dots, \dim(E_A(\lambda_i))\}$ forms a basis of \mathbb{R}^n .

Ex: 1) $A = \begin{bmatrix} 13 & 30 \\ -6 & -14 \end{bmatrix} : u_1 = \begin{bmatrix} 5 \\ -2 \end{bmatrix} : u_2 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$

$E_A(1) = \text{span}(u_1) \quad E_A(-2) = \text{span}(u_2)$

$\dim(E_A(1)) + \dim(E_A(-2)) = 2 = \dim(\mathbb{R}^2)$

\Rightarrow diagonalizable (in fact $\begin{bmatrix} 5 & 2 \\ -2 & -1 \end{bmatrix}^{-1} A \begin{bmatrix} 5 & 2 \\ -2 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix}$)

2) $A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{bmatrix} : u_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} : u_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} : u_3 = \begin{bmatrix} 3 \\ 4 \\ 2 \end{bmatrix}$
 linearly independent.

$\dim(E_A(1)) + \dim(E_A(2)) + \dim(E_A(3)) = 3 = \dim(\mathbb{R}^3)$

$\Rightarrow A$ is diagonalizable.

3) $A = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{bmatrix} : A - \lambda I$ is singular iff $\lambda = 2$

\Rightarrow eigenvalue = 2 only.

$E_A(2) = \text{span}(v)$ $\therefore \dim(E_A(2)) = 1 < \dim(\mathbb{R}^3) = 3$

\therefore Not diagonalizable.

4) $A = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ has no eigenvalues \Rightarrow Not diagonalizable.

* prop: Let A be $n \times n$ matrix which is diagonalizable with

$V^{-1} A U = \text{diagonal matrix } D$ for some invertible U .

Then ① $\forall m \in \mathbb{N}$, A^m is diagonalizable with

$$V^{-1} A^m U = D^m = \text{diagonal}.$$

② If $A = \text{invertible}$, then A^{-1} is diagonalizable.

pf: ① $(V^{-1} A U)^m = (V^{-1} A U)(V^{-1} A U) \cdots (V^{-1} A U)$
 \parallel
 $= V^{-1} A^m U$ $\#$
 $D^m (= \text{diagonal})$

② $V^{-1} A U = D$ $\text{diag}(\lambda_1, \dots, \lambda_n)$

$\because A = \text{invertible} \quad \therefore$ diagonal entry of $D \neq 0$.

$\therefore D$ is invertible. with $D^{-1} = \text{diag}(\lambda_1^{-1}, \dots, \lambda_n^{-1})$

$$D^{-1} = (V^{-1} A U)^{-1} = V^{-1} A^{-1} U \#.$$

Question: How to determine singularity of a matrix??

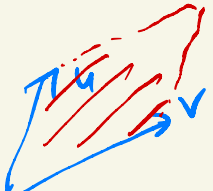

* Finding RREF of A is too much!! (for this purpose)

Motivation: Find a measurement of a matrix.

Size of $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = [u \ v \ w] ??$

- When size = 0 \Rightarrow singular
- size $(AB) = \text{size}(A) \cdot \text{size}(B)$

From vector point of view:

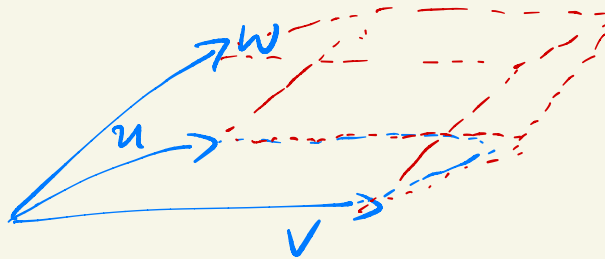
2D: $A = [u \ v]$  "size" of $A \neq$ Area of 

$= |u_1 v_2 - u_2 v_1|$

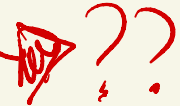
Expectation: size $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = 1 = -\text{size} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$. (using coordinate geom)

3D:

$A = [u \ v \ w]$:



"size" of A (best guess) = volume of parallelepiped = $\begin{vmatrix} u_1 (v_2 w_3 - v_3 w_2) \\ -u_2 (v_1 w_3 - v_3 w_1) \\ +u_3 (v_1 w_2 - v_2 w_1) \end{vmatrix}$ (using coordinate geom.)

} higher dimen?? 

Ans to these \Rightarrow determinant of A , det(A).

Defn: Given a $n \times n$ matrix A and $k, l \in \{1, 2, \dots, n\}$.

$A(k|l) = (n-1) \times (n-1)$ matrix obtained by removing the k -th row, l -th column of A .

Ex:

$$A = \begin{bmatrix} u_1 & v_1 & w_1 \\ u_2 & v_2 & w_2 \\ u_3 & v_3 & w_3 \end{bmatrix}, \quad A(1|1) = \begin{bmatrix} v_2 & w_2 \\ v_3 & w_3 \end{bmatrix}$$

$$A(2|3) = \begin{bmatrix} u_1 & v_1 \\ u_3 & v_3 \end{bmatrix} \text{ etc.}$$

Defn: Given a $n \times n$ matrix A with entry $= A_{ij}$

(a) if $n=1$, $\det A = A_{11}$

(b) if $n > 1$, define $\det A$ inductively on n by.

$$\det(A) = \sum_{j=1}^n (-1)^{j+1} A_{j1} \cdot \det(A_{j|1})$$

Ex: 1) $A = \begin{bmatrix} u_1 & v_1 \\ u_2 & v_2 \end{bmatrix}$, $\det(A) = u_1 \cdot v_2 - u_2 \cdot v_1$

2) $A = \begin{bmatrix} u_1 & v_1 & w_1 \\ u_2 & v_2 & w_2 \\ u_3 & v_3 & w_3 \end{bmatrix}$, $\det(A) = u_1 \cdot \det \begin{bmatrix} v_2 & w_2 \\ v_3 & w_3 \end{bmatrix} = u_1 (v_2 w_3 - v_3 w_2)$

$$- u_2 \det \begin{bmatrix} v_1 & w_1 \\ v_3 & w_3 \end{bmatrix} \left(-u_2 (v_1 w_3 - v_3 w_1) \right)$$

$$+ u_3 \det \begin{bmatrix} v_1 & w_1 \\ v_2 & w_2 \end{bmatrix} \left(+u_3 (v_1 w_2 - v_2 w_1) \right) \quad \#$$

Keep in Mind: There are lots of symmetry in computing $\det(A)$.

Lemma: For $n > 1$, and $k = 1, 2, \dots, n$.

$$\det A = \sum_{j=1}^n (-1)^{j+k} A_{jk} \det(A_{(j|k)}).$$

Ex: $A = \begin{bmatrix} u_1 & v_1 & w_1 \\ u_2 & v_2 & w_2 \\ u_3 & v_3 & w_3 \end{bmatrix}$, then $\det A = -v_1 (u_2 w_3 - u_3 w_2) + v_2 (u_1 w_3 - u_3 w_1) - v_3 (u_1 w_2 - u_2 w_1)$.

Lemma: We also have $\det(A^t) = \det(A)$.

i.e. $\det A = \sum_{j=1}^n (-1)^{j+k} A_{kj} \det(A_{(k|j)}) = \det(A^t)$

Ok, But why care?? (Before we study them further)

Thm: Given a $n \times n$ matrix A , then

$$A = \text{non-singular} \iff \det(A) \neq 0.$$

~~Thm~~ Therefore, to find the eigenvalue of A , we only need to

Solve $\lambda \in \mathbb{R}$ s.t. $\det(A - \lambda I) = 0$
polynomials

Verify it Now: relies on symmetry

Thm (linearity in columns) Suppose A is a $n \times n$ matrix s.t.

$$A = [a_1 \ a_2 \ \dots \ a_k \ \dots \ a_n]$$

$$B = [b_1 \ b_2 \ \dots \ b_k \ \dots \ b_n]$$

$$C = [c_1 \ c_2 \ \dots \ c_k \ \dots \ c_n]$$

where $a_i, b_i, c_i \in \mathbb{R}^n$.

If $a_i = b_i = c_i \quad \forall i \neq k$

$a_k = \lambda b_k + c_k$

then $\det A = \lambda \det B + \det C$.

$$\det \begin{bmatrix} a_1 & a_2 & \dots & \lambda b_k + c_k & \dots & a_n \end{bmatrix} = \det [a_1 \dots b_k \dots a_n] \cdot \lambda + \det [a_1 \dots c_k \dots a_n]$$

Since $\det(A^t) = \det(A)$, linearity also holds along rows:

Thm: Suppose $A = nxn$ matrix, then

$$\det \begin{bmatrix} r_1 \\ \vdots \\ r_{k-1} \\ \lambda s_k + t_k \\ r_{k+1} \\ \vdots \\ r_n \end{bmatrix} = \det \begin{bmatrix} r_1 \\ \vdots \\ r_{k-1} \\ s_k \\ r_{k+1} \\ \vdots \\ r_n \end{bmatrix} \cdot \lambda + \det \begin{bmatrix} r_1 \\ \vdots \\ r_{k-1} \\ t_k \\ r_{k+1} \\ \vdots \\ r_n \end{bmatrix}$$

where $r_i^t \in \mathbb{R}^n$ and $s_k^t, t_k^t \in \mathbb{R}^n$.

Rule: Putting $\lambda = -1$, we have

Thm: $\det [a_1 \dots a_{k-1} \quad -a_k \quad a_{k+1} \dots a_n] = -\det [a_1 \dots a_k \dots a_n]$

eg: $\det \begin{bmatrix} u_1 & -v_1 & w_1 \\ u_2 & -v_2 & w_2 \\ u_3 & -v_3 & w_3 \end{bmatrix} = -\det \begin{bmatrix} u_1 & v_1 & w_1 \\ u_2 & v_2 & w_2 \\ u_3 & v_3 & w_3 \end{bmatrix}$

Thm: $\det [a_1 \dots a_{p-1} \quad a_p \quad a_{p+1} \dots a_{q-1} \quad a_q \quad a_{q+1} \dots a_n] = -\det [a_1 \dots a_{p-1} \quad a_p \quad a_{q+1} \dots a_q \quad a_{q+1} \dots a_n]$

(anti-symmetric upon interchanging columns)

eg: $\det \begin{bmatrix} u_1 & v_1 & w_1 \\ u_2 & v_2 & w_2 \\ u_3 & v_3 & w_3 \end{bmatrix} = -\det \begin{bmatrix} w_1 & v_1 & u_1 \\ w_2 & v_2 & u_2 \\ w_3 & v_3 & u_3 \end{bmatrix}$



Trivial case of thm: Given a nxn matrix A.

① If there are two identical columns of A, then $\det(A) = 0$.

(\Downarrow A is singular \Uparrow)

② If there is a column of A s.t. it is linear combination of others, then $\det A = 0$.

pf: case ① : $\det [a_1 \dots \overset{p\text{-th}}{\downarrow} a_p \dots \overset{q\text{-th}}{\downarrow} a_q \dots a_n]$
 $= -\det [a_1 \dots a_q \dots a_p \dots a_n]$
 $= -\det [a_1 \dots a_p \dots a_q \dots a_n] \quad \because a_p = a_q$

$\Rightarrow \det A = 0$.

case ② : $\det A = \det [a_1 \dots a_p \dots a_n]$

(where $a_p = \sum_{i \neq p} \lambda_i a_i$)

$= \sum_{i \neq p} \lambda_i \det [a_1 \dots \overset{p\text{-th column}}{a_i} \dots a_n]$

$= \sum_{i \neq p} \lambda_i \cdot 0 \quad \text{by } \textcircled{1}$

$= 0 \quad \#$